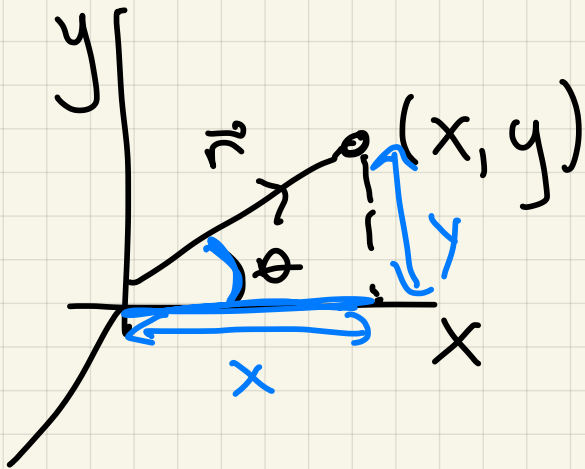


Circular motion

ex: Object spun in a circle
on the end of a string.

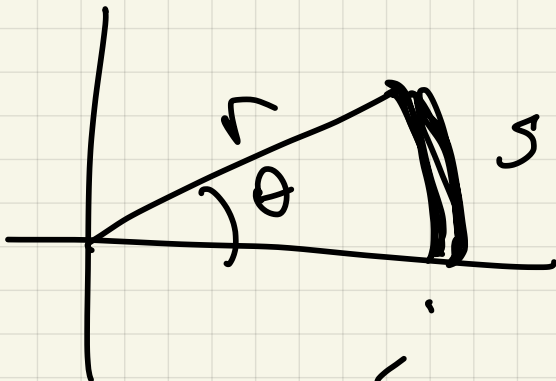


position vector

$$\vec{r} = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$x = r \cos \theta$$

$$y = r \sin \theta$$



$s = \text{arc length}$

$$s = r \theta$$

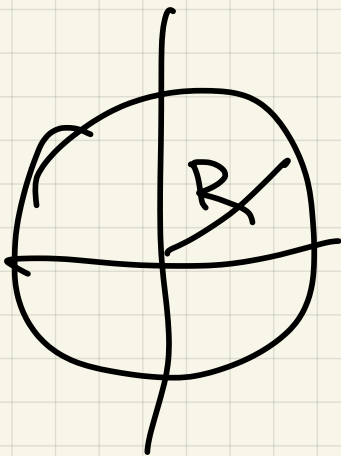
Circumference

$$C = r(2\pi)$$

For circular motion, s (arc length) is the path of the object.

$v =$ derivative of position

$$v = \frac{ds}{dt} = \frac{d}{dt}(r\theta)$$



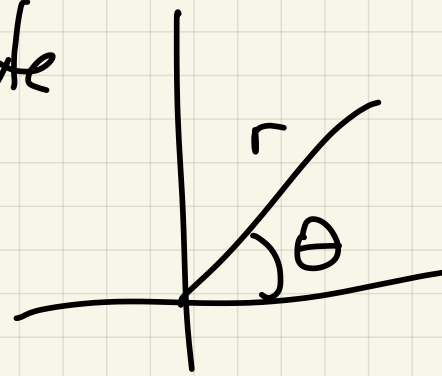
For circles, $r = R$
a constant

$$v = R \left(\frac{d\theta}{dt} \right)$$

Greek omega $\left[\omega \equiv \frac{d\theta}{dt} \right]$ $\theta =$ angle of polar coordinate

$\theta \equiv$ polar coordinate

\equiv angular position



For a circle where $r=R$ a constant, θ defines position

$\omega \equiv$ angular velocity
is a vector

for now, CW or CCW

units $\frac{\text{rad}}{\text{s}}$ \leftarrow radians
are a unitless unit

$$s = R\theta$$

\downarrow \downarrow
m m

Def $1 \text{ rad} = \frac{\text{arc length } s}{R}$

$$\pi \text{ rad} = 180^\circ$$

Uniform Circular motion

$$r = R = \text{constant}$$

ω is a constant

We can write

$$\theta = \omega t$$

only for uniform
Circ. motion

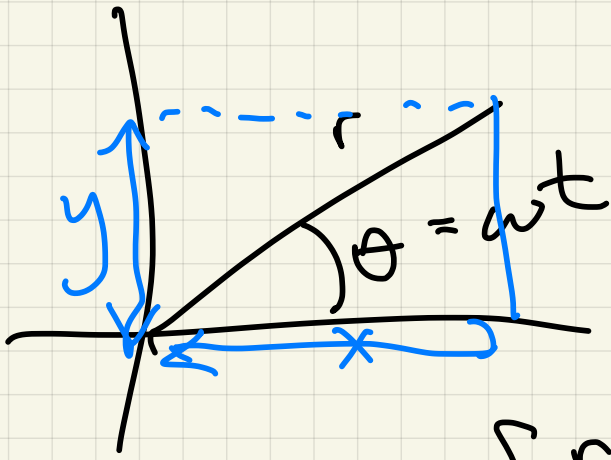
Preview Ch 8

$$\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

Ch 8

ω_0
ang velocity

α
angular acc.



$$\vec{r} = \begin{bmatrix} r \cos \theta \\ r \sin \theta \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$$

uniform circular

$r = R$ a const

$\theta = \omega t$ where $\omega = \text{const}$

$$\vec{r} = \begin{bmatrix} R \cos(\omega t) \\ R \sin(\omega t) \end{bmatrix}$$

velocity is derivative

$$\vec{v} = \frac{d\vec{r}}{dt} = \begin{bmatrix} -\omega R \sin(\omega t) \\ +\omega R \cos(\omega t) \end{bmatrix}$$

Q: Magnitude of velocity?

$$|v|^2 = v_x^2 + v_y^2$$

$$= [-\omega R \sin(\omega t)]^2 + [\omega R \cos(\omega t)]^2$$

$$= \omega^2 R^2 \sin^2(\omega t) + \omega^2 R^2 \cos^2(\omega t)$$

$$= \omega^2 R^2 \{ \sin^2(\omega t) + \cos^2(\omega t) \}$$

$$v^2 = \omega^2 R^2$$

$$v = R\omega \quad \leftarrow \text{magnitude only}$$

same answer from
s (arc length)

Back to velocity vector
to get acc vector.

$$\vec{v} = \begin{bmatrix} -\omega R \sin(\omega t) \\ \omega R \cos(\omega t) \end{bmatrix}$$

$$\vec{a} = \frac{d\vec{v}}{dt} = \begin{bmatrix} -\omega^2 R \cos(\omega t) \\ -\omega^2 R \sin(\omega t) \end{bmatrix}$$

$$\vec{a} = -\omega^2 \vec{r}$$

acceleration

ω^2 const

original position vector
 \Rightarrow along a radius of circle

\vec{r} = points radially outward

$-\vec{r}$ = toward center of circle
 \Rightarrow centripetal

centripetal is a direction

$\left. \begin{matrix} x \\ y \end{matrix} \right\}$ can be directions

$\left[\begin{matrix} \text{centripetal} \\ \text{tangential} \end{matrix} \right]$

$$\vec{a} = -\omega^2 \vec{r}$$

↑

acceleration for uniform circular motion is always toward the center of the circle.

⇒ We call it

centripetal acceleration

$$\vec{a} = -\omega^2 \vec{r}$$

Book usually writes

$$a_c = \frac{v^2}{r}$$

$$\begin{aligned} |\vec{a}| &= |-\omega^2 \vec{r}| \\ a &= r\omega^2 \\ &= r \left(\frac{v}{r} \right)^2 \\ &= \frac{v^2}{r} \end{aligned}$$

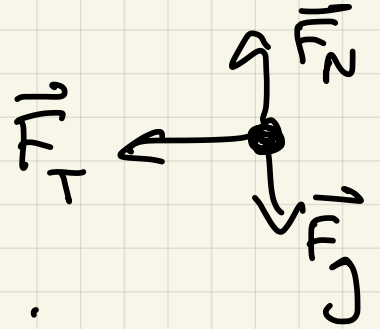
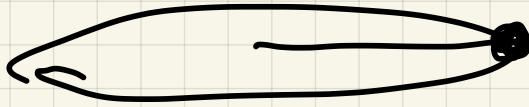
We can also say

$$\sum \vec{F}_c = m a_c$$

\sum of forces
in centripetal
dir

acc in
centripetal
dir.

Ex!: A 2 kg mass on the end of a string spins in a circle of radius 40 cm.



The tension in the string is 45 N.

If it's moving in uniform circular motion, what is the object's speed?

$$\Sigma F_c = ma_c$$

$$F_T = m \frac{v^2}{r}$$

$$v = \sqrt{\frac{r F_T}{m}} = \sqrt{\frac{(4\text{m}) 45\text{N}}{2\text{kg}}}$$
$$v = 3\text{ m/s}$$

